

VP, VNP, determinantal complexity of permanent

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Last lecture:-

We defined VP, VNP, showed $(\text{perm}_n) \in \text{VNP}$

Prop $(\text{det}_n) \in \text{VP}$

Proof Let S_n act on $\mathbb{C}[x_1, \dots, x_n]$ naturally, and let

$\mathbb{C}[x_1, \dots, x_n]^{S_n}$ the invariant subspace.

Fact 1 The elementary symmetric functions

$$e_r = \sum_{\substack{J \subseteq [n] \\ |J|=r}} x_{j_1} \dots x_{j_r} \quad \text{are a basis of } \mathbb{C}[x_1, \dots, x_n]^{S_n}$$

Fact 2 The power sum polynomials

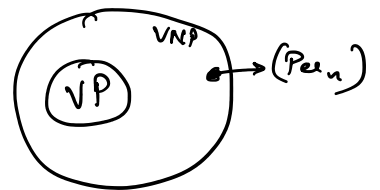
$$p_r = x_1^r + \dots + x_n^r \quad \text{are also a basis of } \mathbb{C}[x_1, \dots, x_n]^{S_n}$$

(*) The determinant of $f: V \rightarrow V$ is the product of the eigenvalues $\lambda_1, \dots, \lambda_n$

$$(*) \text{ Trace}(f) = \sum_{i=1}^n \lambda_i, \quad \text{trace}(f^k) = \sum_{i=1}^n \lambda_i^k$$

f^k can be computed with small circuits, so $\det(f)$ also can be computed using small circuits \square

Thm [Valiant] (Perm_n) is VNP-complete.
(Chor $k \neq 2$)



Conjecture [Valiant] $\text{VP} \neq \text{VNP}$

Thm [Burgisser] $\text{VP} = \text{VNP} \Rightarrow \text{P/Poly} = \text{NP/Poly}$ (assuming Gen. Riemann Hyp.)

\downarrow non-uniform Polynomial time \downarrow non-uniform NP

Class of decision problems

Polynomial
time

NP

Class of decision problems
solvable by a family of polynomial
size boolean circuits + the circuit
family can be non-uniform, i.e.
they could be a completely diff.
circuit for each input length.

- VP vs VNP "arithmetic circuit complexity"
- P/poly vs NP/poly "boolean circuit complexity"
- P vs NP "uniform complexity"
- * VP vs VNP has strong impact on what is called the polynomial hierarchy.

* Graph G with adj matrix A , the permanent of A counts the no. of perfect matchings
checking for presence of perfect matching $\in P$, but enumerator is hard.

Determinantal Complexity

Defn $\mathcal{I}: \mathbb{C} \cup \{x_1, \dots, x_n\}$.

- Every elem of \mathcal{I} is an expression
- $\text{expr}_1 * \text{expr}_2$ & $\text{expr}_1 + \text{expr}_2$ are also expressions

The size of an expression is defined as the no. of + 's or * 's

Thus every expression is a polynomial in $\mathbb{C}[x_1, \dots, x_n]$. For $f \in \mathbb{C}[x_1, \dots, x_n]$,

$$\text{expression size of } f = \min_{\phi \text{ computes } f} |\phi|$$

Thm [Universality of the determinant & permanent]

$\forall f \in \mathbb{C}[x_1, \dots, x_n]$ of expr size u , there is a matrix M of size $(u+2) \times (u+2)$
s.t. $\det M = f$

entries of M are linear
forms in x_1, \dots, x_n

(also true for permanent)

forms in x_1, \dots, x_n

(also true for permanent)

Def min size of matrix in above thm is called the determinantal complexity of f , denoted $dc(f)$

Thm $dc(\text{perm}_m) \leq O(m^c)$, c is a const. $\implies VP = VNP$

Proof by defn \square

Goal: $\frac{m^2}{2} \leq dc(\text{perm}_m) \leq 2^m - 1$

$\longleftarrow dc(\text{perm}_m) \geq \frac{m^2}{2} \longrightarrow$

Overview

- ① Define Gauss maps
 - ② Notion of degeneracy of Gauss images
 - ③ Show that - perm does not have degenerate Gauss images
 - det has "strongly" degenerate Gauss images
- lower bound follows from a dimension count

GAUSS MAPS

Maps points in 3 space to its unit normal vector on the unit sphere $\subseteq \mathbb{R}^3$

Defn [Gauss map for surfaces in \mathbb{R}^3] $M \subseteq \mathbb{R}^3$ is an oriented surface. N is the Gauss map of M

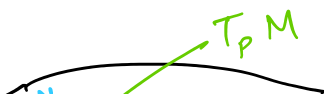
Gauss map of M

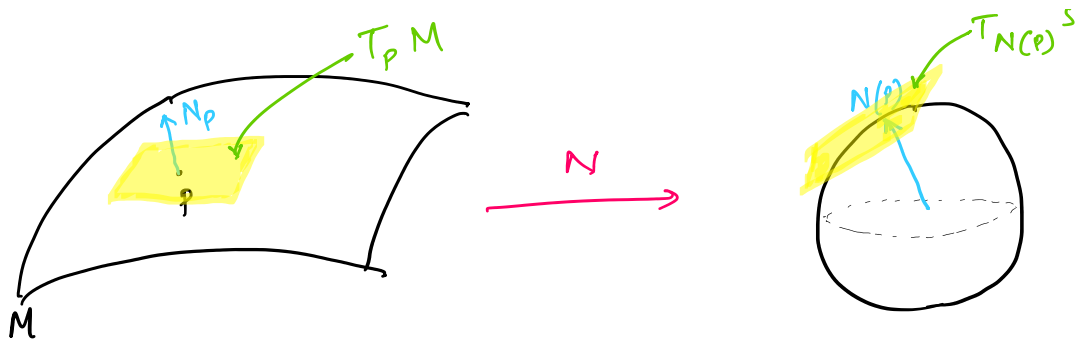
$N: M \rightarrow S^2 (\subseteq \mathbb{R}^3)$
 $p \mapsto N_p$ (oriented unit normal vector at point p)

\swarrow unit sphere

(Continuous)

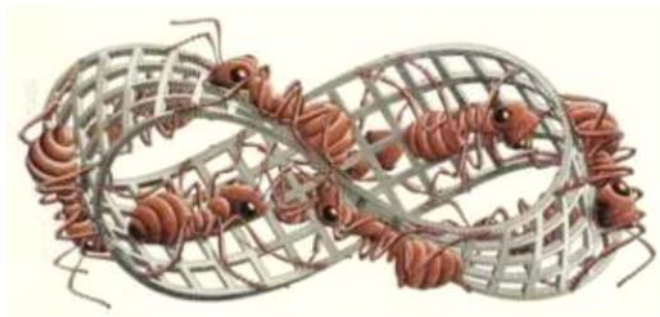
$(\|N_p\| = 1, \langle N_p, \vec{v} \rangle = 0 \ \forall \vec{v} \in T_p M)$





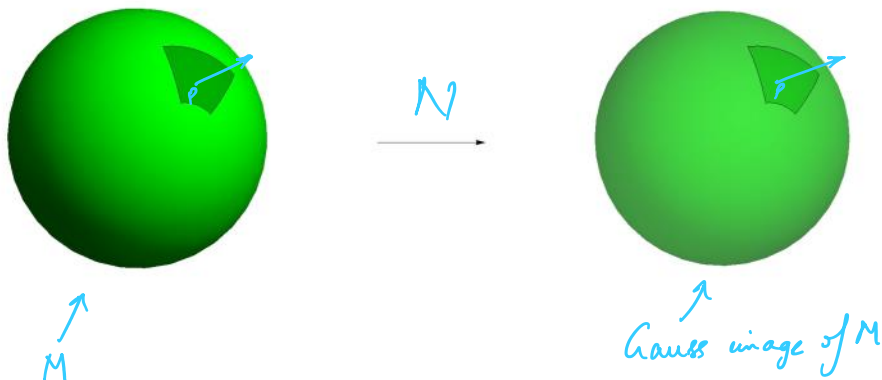
$$T_p M \cong T_{N(p)} S^2$$

- ① Most surfaces have two choices for the direction of normal vector
- ② N need to be cont., so some surfaces do not have a Gauss map
e.g. Mobius strip

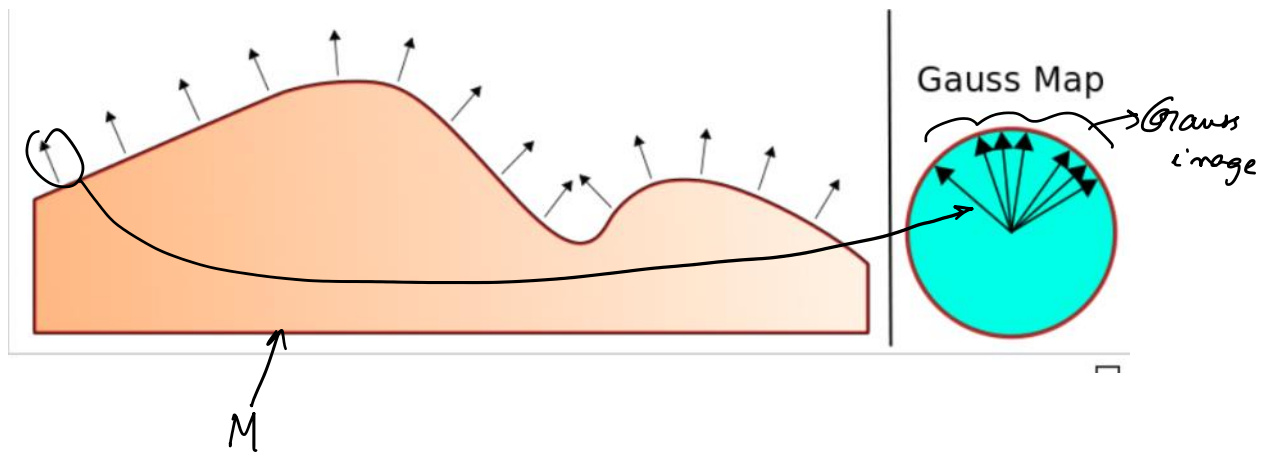


Möbius Band

Example ①



②



(3) Gauss image has lower dim. than M .

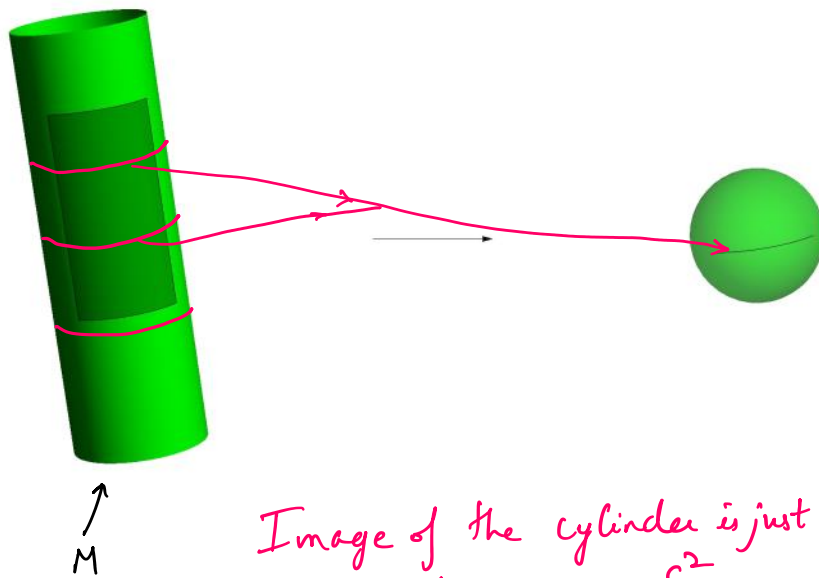


Image of the cylinder is just a great circle on S^2

$$2 = \dim(M) > \dim(\text{great circle}) = 1$$

(4) Gauss image of a plane in \mathbb{R}^3 is just a point (0-dim)
(2 dim)

Thm [Segre 1910] Let $M \subseteq \mathbb{P}^3$ be a surface with degenerate Gauss image. Then it is one of

- (1) A linearly embedded \mathbb{P}^2
- (2) A cone over a curve C
- (3) A tangential variety to a curve C .

... ..

③ A tangential variety to a curve C .

"Having a degenerate Gauss image is a pathology"

Notation ① V -vector space $\pi: V \setminus \{0\} \rightarrow \mathbb{P}V$
 $y \mapsto [y]$

② $X \subseteq \mathbb{P}V$, define

$$(V \supseteq) \hat{X} := \pi^{-1}(X) \cup \{0\}$$

③ If \hat{X} is a variety, $X \subseteq \mathbb{P}V$ will also be called a variety.

Defn $X \subseteq \mathbb{P}V$ be an irred. proj. variety.

[Affine Tangent space] $T_{[x]} X$ is just $T_x \hat{X} = T_{[x]} X$
 at $[x] \in X$ ↑
any pt. in V
representing $[x] \in \mathbb{P}V$

[Projective tangent space] $\mathbb{P}(T_x \hat{X})$

Defn [Conormal space] $X \subseteq \mathbb{P}V$ (proj. variety). The conormal space at $[x] \in X$, denoted $N_{[x]}^* X \subseteq V^*$ is just the annihilator of $T_{[x]} \hat{X}$, i.e.

$$N_{[x]}^* X = (T_{[x]} \hat{X})^\perp$$

Defn [Gauss image in general] $X \subseteq \mathbb{P}V$ be an irred. hypersurface. Define the Gauss image / Dual variety of X

Gauss image / Dual variety of X

$$X^V := \left\{ H \in \mathbb{P}V^* \mid \exists [x] \in X_{\text{smooth}}, T_{[x]} \hat{X} \subseteq H \right\}$$

$$= \left\{ H \in \mathbb{P}V^* \mid \exists [x] \in X_{\text{smooth}}, H \in \mathbb{P} N_{[x]}^* X \right\}$$

↑
points

↑
hyperplanes in $\mathbb{P}V^*$
determined by H

Union of all conormal lines in $\mathbb{P}V^*$

If X^V is not a hypersurface, we say X has a degenerate Gauss image

- * Perm hypersurface does not have a degenerate dual variety
- * det hypersurface has a degenerate dual variety.

(det_m hypersurface)^V has low dimension $\approx n$

(Perm_m hyp)^V has high dimension $\approx m^2$

$$m^2 \lesssim n$$

— Let V be a v.s. over field K .

Ring of polynomial functions V is denoted $K[V]$.

— $K[V]$ consists of polynomials in t_i , where t_i form a basis of V .

— If K is infinite, $K[V]$ is the symmetric algebra on V^* , i.e. $\text{Sym}(V^*)$

→ $\text{Sym}^q(V^*)$ — v.s. of multilinear functionals. (Symmetric)

$$\lambda: \prod_{i=1}^q V \rightarrow K$$

→ Any $\lambda \in \text{Sym}^q(V^*)$ gives you a homogeneous poly func of degree q .

$$f(v) = \lambda(v, \dots, v)$$

Thus $\text{Sym}^q(V^*) \rightarrow K[V]_{(q)}$ is an isomorphism

Elements of $\text{Sym}^q(\mathbb{C}^M)$ (a) hom. poly. of deg q on $(\mathbb{C}^M)^*$

(b) a symmetric tensor

(c) — homogeneous differential operators of order q on the

(b) a symmetric tensor

(c) a homogeneous differential operator of order t on the space of polynomials, i.e. $\text{Sym}((\mathbb{C}^n)^*)$

Idea: $k[x_1, \dots, x_n]$ is a vector space

$$\frac{\partial}{\partial x_i} \text{ maps an elem of } k[x_1, \dots, x_n]_{(q)} \cong \text{Sym}^q(V^*)$$

to an elem of

$$k[x_1, \dots, x_n]_{(q-1)} \cong \text{Sym}^{q-1}(V^*)$$

Defn Let $r \geq t$ $\text{Sym}^r(V^*) \otimes \text{Sym}^t(V) \rightarrow \text{Sym}^{r-t}(V^*)$

[Contraction map]

↓
homogeneous diff operators of order t

Let $P \in \text{Sym}^n \mathbb{C}^N$, $(\mathbb{C}^N)^*$ can be considered as the space of first order homogeneous diff. operators on $\text{Sym}^n \mathbb{C}^N$. Define

$$P_{1, n-1} : (\mathbb{C}^N)^* \rightarrow \text{Sym}^{n-1}(\mathbb{C}^N)$$

$$\frac{\partial}{\partial x_j} \longmapsto \frac{\partial P}{\partial x_j}$$

$$\left[\begin{array}{l} \text{Co-ord free } \text{Sym}^n V \subseteq V \otimes \text{Sym}^{n-1} V = \text{Hom}(V^*, \text{Sym}^{n-1} V) \\ P \in \text{Sym}^n V, P_{1, n-1} \in \text{Hom}(V^*, \text{Sym}^{n-1} V) \end{array} \right]$$

Define $P_{2, n-2} : \text{Sym}^2((\mathbb{C}^N)^*) \rightarrow \text{Sym}^{n-2} \mathbb{C}^N$

$$\frac{\partial^2}{\partial x_i \partial x_j} \longmapsto \frac{\partial^2 P}{\partial x_i \partial x_j}$$

$$P_{k, n-k} : \text{Sym}^k((\mathbb{C}^N)^*) \rightarrow \text{Sym}^{n-k} \mathbb{C}^N$$

$$D \longmapsto D(P)$$

$P \in \text{Sym}^d V^*$ be irreducible. Let $[x] \in Z(P)$ be

Prop Let $P \in \text{Sym}^d V^*$ be irreducible. Let $[x] \in Z(P)$ be a general pt. Then

$$\dim Z(P)^V = \text{rank} \left(P_{d-2,2}(x) \right) - 2$$

$\Rightarrow P_{d-2,2}(x) \in \text{Sym}^2 V^*$, a symmetric matrix,

$P_{d-2,2}(x)$ is the Hessian of P .

Prop Let $Q \in \text{Sym}^m \mathbb{C}^M$, $\tilde{A}: \mathbb{C}^M \rightarrow \mathbb{C}^N$ be such that

$$Q(y) = P(\tilde{A}(y)) \quad \forall y \in (\mathbb{C}^M)^*$$

\times

$$\text{rank} \left(Q_{n-2,2}(y) \right) \leq \text{rank} \left(P_{n-2,2}(\tilde{A}(y)) \right)$$

Remaining

① $\text{rank} \left((P_{\text{perm}})_{m-2,2}(x) \right)$ for general $[x] \in Z(P_{\text{perm}})$ is full, i.e. there is a pt. where the matrix has rank $\frac{m^2}{2}$

② $\dim Z(\det_n)^V = 2n-2$
 $\Rightarrow \text{rank} \left((\det_n)_{n-2,2}(x) \right) = 2n$ for $[x] \in Z(\det_n)$ ^{general}

③ By \times Gauss image of $\{ \det(f(x)) = 0 \}$, for $f: \mathbb{C}^{m^2} \rightarrow \mathbb{C}^{n^2}$ is as degenerate as the Gauss map of

$$\{ \det(x) = 0 \}, \text{ we have } m^2 \leq 2n$$

$$\Rightarrow n \geq \frac{m^2}{2}$$

To show that a hypersurface has non-degenerate Gauss image, find a pt. where Hessian of its defining eqn. has max. rank.

Lemma There exists such a pt. for P_{perm}

Proof Consider

$$y_0 = \begin{pmatrix} 1-m & 1 & \dots & 1 \\ 1 & \dots & \dots & \dots \\ \vdots & \dots & \dots & \dots \\ 1 & \dots & \dots & 1 \end{pmatrix}$$

Easy to check
 $\text{Perm}(y_0) = 0$

$$y_0 \in Z(\text{Perm}_m)$$

To compute

$$(\text{Perm}_m)_{m-2,2}(y_0), \text{ note}$$

$$\frac{\partial^2}{\partial y_{ij} \partial y_{kl}} \text{Perm}_m \begin{bmatrix} y_{1,1} & \dots & y_{1,m} \\ \vdots & & \vdots \\ y_{m,1} & \dots & y_{m,m} \end{bmatrix} = \begin{cases} 0 & \text{if } i=k \text{ or } j=l \\ \text{Perm}_{m-2} \left(\hat{Y}_{(ij), (kl)} \right) & \text{otherwise} \end{cases}$$

\uparrow
 Y

\uparrow
 rows i, k
 $\&$
 cols j, l removed

$$M = \begin{pmatrix} 0 & Q & Q & \dots & Q \\ Q & 0 & R & \dots & R \\ Q & R & 0 & \dots & R \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ Q & R & \dots & \dots & R \end{pmatrix} \in \mathbb{C}^{m^2 \times m^2}, \text{ where}$$

$$Q =_{m-2} \begin{pmatrix} 0 & 1 & \dots & 1 & 1 \\ 1 & 0 & \dots & 1 & 1 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 1 & 1 & \dots & 0 & 0 \end{pmatrix}, \text{ and } m \times m$$

$$R = \begin{pmatrix} 0 & m-2 & \dots & m-2 \\ m-2 & 0 & -2 & \dots & -2 \\ \vdots & -2 & 0 & \dots & -2 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ m-2 & -2 & \dots & \dots & 0 \end{pmatrix} m \times m$$

NTS M is invertible. wlog $Q = Id_m$

$$\dots \dots (v_1 \quad v_2 \quad \dots \quad v_{m-1} \quad \dots \quad v_{m,1} \quad \dots \quad v_{m,m})$$

NTS M is invertible. w.l.o.g.

$$\text{Let } V = \underbrace{(v_{1,1} \dots v_{1,m})}_{\tilde{V}_1} \underbrace{(v_{2,1} \dots v_{2,m})}_{\tilde{V}_2} \dots \underbrace{(v_{m,1} \dots v_{m,m})}_{\tilde{V}_m}$$

\uparrow
Ker M

$$MV = 0$$

$$\tilde{V}_2 + \dots + \tilde{V}_m = 0$$

$$\tilde{V}_1 + R\tilde{V}_3 + \dots + R\tilde{V}_m = 0$$

⋮

$$\tilde{V}_1 + R\tilde{V}_2 + \dots + R\tilde{V}_{m-1} = 0$$

$$\tilde{V}_2 + \dots + \tilde{V}_m = 0$$

$$R\tilde{V}_2 = 0$$

$$\Leftrightarrow R\tilde{V}_3 = 0$$

⋮

$$R\tilde{V}_m = 0$$

$$\rightarrow (m-1)\tilde{V}_1 = 0 \Rightarrow \tilde{V}_1 = 0 \Rightarrow \tilde{V}_2 = \dots = \tilde{V}_m = 0$$

Thus Ker M is trivial \square